Discrete and Computational Geometry, WS1415 Exercise Sheet "6": Dilations

University of Bonn, Department of Computer Science I

- Written solutions have to be prepared until Tuesday 25th of November 14:00 pm. There will be a letterbox in the LBH building.
- You may work in groups of at most two participants.
- Please contact Hilko Delonge, hilko.delonge@uni-bonn.de, if you want to participate and have not yet signed up for one of the exercise groups.
- If you are not yet subscribed to the mailing list, please do so at https://lists.iai.uni-bonn.de/mailman/listinfo.cgi/lc-dcgeom

Exercise 16: Visibility and maximum dilation (4 Points)

The graph-theoretic dilation of a planar graph G with vertex set V is

$$\delta_{graph}(G) := \sup_{p \neq q \in V} \frac{|\pi_p^q|}{|pq|}$$

where |pq| is the euclidean distance from p to q and $|\pi_p^q|$ is the length of a shortest path in G from p to q.

- Construct a planar graph G where the maximum graph-theoretic dilation of G is attained by a pair of non-visible vertices.
- Recall the definition of geometric dilation of a planar graph. Prove that for a planar, simply connected graph G there is always a pair of points $p, q \in G$ with maximal dilation so that p and q are co-visible.

Exercise 17: Dilation and AVDs

(4 Points)

The decision problem for the geometric dilation of a polygonal chain $C = (p_1, p_2, \ldots, p_n)$ was translated into the problem of tracing the chain C through an additively weighted Voronoi diagram.

We proved the following statement: If for a point $(q_x, q_y) \in C$ appearing after $C_i = (p_1, p_2, \ldots, p_i)$ on C, the point (q_x, q_y, a_q) with $a_q := \frac{|C_{p_1}^q|}{K}$ lies below any cone K_{p_i} starting at height $a_{p_i} := \frac{|C_{p_1}^{p_i}|}{K}$ at p_i , the dilation $\delta_C(p_i, q)$ between q and p_i is smaller than K.

- Why do we trace the chain $p_i, p_{i+1}, \ldots, p_n$ through the additively weighted Voronoi diagram of p_1, p_2, \ldots, p_i with weights a_{p_i} ?
- Why can we compute the Voronoi diagram for all points p_1, p_2, \ldots, p_n with weights a_{p_i} and trace the complete chain (for one direction) only once? Or the other way round: Why is it not necessary to incrementally compute the Voronoi diagrams for p_1, p_2, \ldots, p_i and successively trace the chains $p_i, p_{i+1}, \ldots, p_n$?