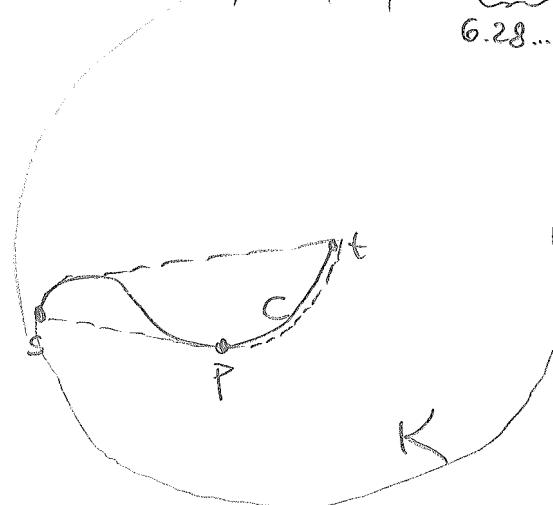


(1)

From the Main Lemma, we can derive an upper bound to the length of self-approaching curves. directly

Lemma 4 Let C be an oriented self-approaching curve from s to t . Then, $|C| \leq \underbrace{2\pi}_{6.28\dots} |st|$

Proof



For each $p \in C$, we have
 $|pt| \leq |st|$
 $\Rightarrow C \subseteq \text{circle } K \text{ of radius } |st| \text{ and}$

$$\xrightarrow{\text{convexity}} |\partial \text{conv}(C)| \leq |\partial K| = 2\pi |st|. \quad \boxed{\text{Lemma 4}}$$

A more careful analysis results in the upper bound of $5.333\dots$ mentioned in the Theorem. It is attained by curves like this

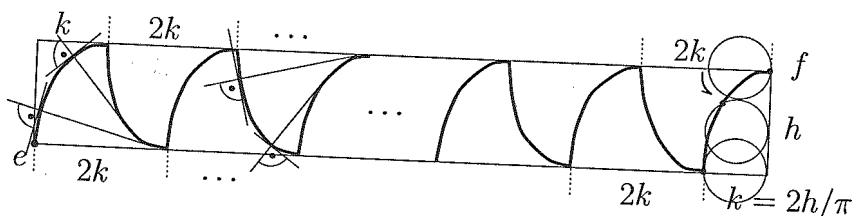
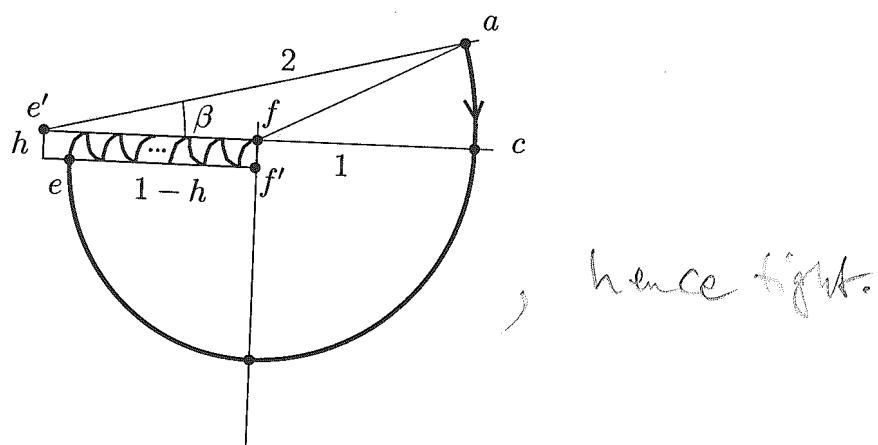


Figure 12: How to fill a rectangle of width w and height h with a self-approaching curve of length $2w$ using pieces of cycloids.



Corollary There exists a $5.3331\ldots$ -competitive strategy for finding the Kernel of a simple polygon. (K)

While 5.3331 -bound on self-approaching curves is tight, there are better strategies (better analysis) for Kernel finding:

Lee / Chwa : $\pi + 1 = 4.141\ldots$ bound for CGS '91

Lee et al : $1 + 2\sqrt{e} \approx 3.828\ldots$ by different strategy

The k -server problem

On a line: Given: k servers (servers) in initial positions on the line

Problem Decide which server should handle request, in order to minimize total path length!

s_1, s_2, \dots, s_k

Sequence of service requests at positions p_1, p_2, p_3, \dots

Remark Gas or maintenance company would perhaps prefer to minimize customer waiting time, instead of the overall gas fill.

Natural idea: Greedy algorithm: always move nearest server to request location

Example $k=2$



request sequence $\tau(pq)^\infty$:

Greedy: moves s_2 to τ ; stays there
oscillates s_1 between p and q

OPT: moves s_2 to τ
 s_1 to p
 s_2 to q and stays there

Lemma Even for $k=2$ servers on the line, the Greedy strategy is not competitive.

Question: Is there a competitive strategy?

Lower bound for very general setting:
(M, d) a metric space, i.e.,

b

$d : M \times M \rightarrow \mathbb{R}_{\geq 0}$ metric, satisfying (ii)

$$\forall x, y, z \in M:$$

$$d(x, y) = 0 \Leftrightarrow x = y$$

$$d(x, y) = d(y, x)$$

$$d(x, y) \leq d(x, z) + d(z, y)$$

Theorem Let (M, d) be a metric space, $k \in \mathbb{N}, t \in \mathbb{N}$. Then, no strategy for the k -Server Problem in (M, d) can be better than k -competitive.

Proof Let A be a k -server algorithm, $p_1, p_2, \dots, p_k \in M$ the initial server locations.

Add $(k+1)$ -th point p_0 .

"Bad" request sequence δ for A : $(x_1, x_2, \dots, x_{m+1}) =$ request always the position where no server is located (the hole) $x_1 = p_0, \dots$

Then, strategy A always moves server from $\underbrace{x_{t+1}}_{\text{next hole}}$ to $\underbrace{x_t}_{\text{pre hole}}$

$$\Rightarrow \text{cost}_A(\delta) = \sum_{t=1}^m d(x_{t+1}, x_t).$$

Define algorithms B_i , $1 \leq i \leq k$ as follows

initially, B_i covers all positions but p_i

On request $x_t = p_i$, B_i moves server from x_{t-1} to x_t

Claim Let S_i := server positions of B_i at time t
Then, $\forall i, j : S_i \neq S_j$

Proof by induction on t . $t=0$: by definition.

Assume request $x_t \in S_i \cap S_j$: no move necessary
claim still holds

Assume $x_t \in S_j$, $\notin S_i$: B_i moves server from x_{t-1} to x_t

$\Rightarrow x_{t-1} \notin S_i$ but

$x_{t-1} \in S_j = S_i$ because of previous requ

$$c \Rightarrow s_i' \neq s_j' \quad [\text{claim}]$$

Claim \Rightarrow at request of x_t , at most one s_i has to move server (from x_{t-1} to x_t)

$$\Rightarrow \sum_{i=1}^k \text{cost}_{S_i'}(\beta) = \sum_{i=2}^{m+1} d(x_{t-1}, x_t) = \text{cost}_A(\beta)$$

$$\Rightarrow \exists i : \text{cost}_{S_i'}(\beta) \leq \frac{1}{k} \text{cost}_A(\beta) \quad [\text{Theorem}]$$

Question Can lower bound of k be attained?

Answer not known for general metric spaces.

Will look at two special cases.

k servers on the line Strategy DC (= double coverage)



on request x left of s_i or right of s_k :

move s_i (resp., s_k) to x (same as greedy)

on request x between s_i, s_j

move closer one of s_i, s_j to x

and the other one towards x by same distance

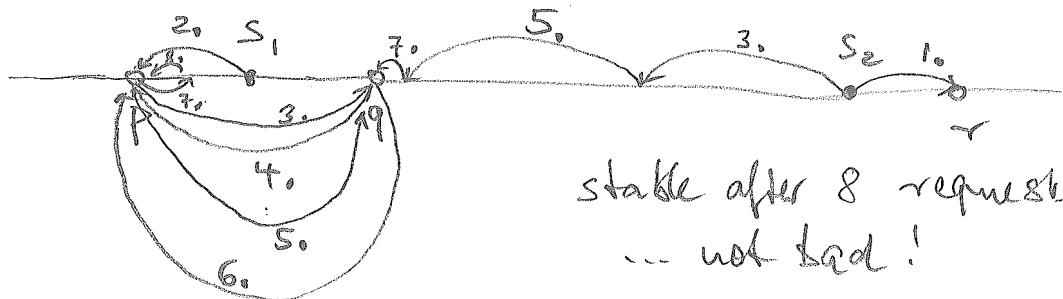


(looks strange at first glance)

d

old example: request sequence $r \in \{1, 2, 3\}^{\infty}$

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Theorem Strategy DC is k -competitive for k servers on the line.

Proof Uses a general technique, interesting in its own right: potential function ($\hat{=}$ bank account)
Idea: actions have immediate consequences but also (structural) long term effects.

More precisely,

let $\mathcal{Z}_{ALG}, \mathcal{Z}_{OPT}$ the state sets of ALG and OPT
and

$$\phi: \mathcal{Z}_{ALG} \times \mathcal{Z}_{OPT} \rightarrow \mathbb{R}$$

a potential function satisfying the following axioms.

Let $\delta = e_1, e_2, \dots, e_n$ denote sequence of moves of ALG and OPT (not necessarily in turns)

- (i) if e_i move of ALG : $ALG(e_i) \leq \phi_{i-1} - \phi_i$
- (ii) if e_i move of OPT : $OPT(e_i) \geq \phi_i - \phi_{i-1}$
- (iii) $\forall i: \phi_i \geq u$ for some constant u .

Lemma Under these assumptions, ALG is c -competitive.

e

Proof Let $A = \{i \mid e_i \text{ is move of ALG}\}$

By the axioms,

$$\text{ALG}(\delta) \leq \sum_{i \in A} (\phi_{i-1} - \phi_i)$$

$$c \text{OPT}(\delta) \geq \sum_{i \in A^c} (\phi_i - \phi_{i-1})$$

\Rightarrow it is sufficient to show the following:
there exists additive constant V such that

$$\sum_{i \in A} (\phi_{i-1} - \phi_i) \stackrel{!}{\leq} \sum_{i \in A^c} (\phi_i - \phi_{i-1}) + V$$

$$\Leftrightarrow \underbrace{\sum_{i \in A} \phi_{i-1} + \sum_{i \in A^c} \phi_{i-1}}_{\sum_{i=1}^n \phi_{i-1}} \stackrel{!}{\leq} \underbrace{\sum_{i \in A} \phi_i + \sum_{i \in A^c} \phi_i}_{\sum_{i=1}^n \phi_i} + V$$

$$\Leftrightarrow \phi_0 \stackrel{!}{\leq} \phi_n + V$$

can be fulfilled by $V := \phi_0 - u$, since $\phi_n \geq u$

Lemmas

Big question: Which potential function ϕ to use
in proving DC is k -competitive?

Def: $\phi := k \cdot M_{\min} + \sum_{DC} \quad \text{where}$

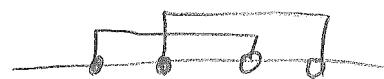
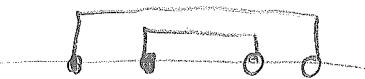
$M_{\min} :=$ cost of minimum matching between
server positions of $\text{ALG} = \text{DC}$ and OPT

$\sum_{DC} :=$ sum of all distances between
server positions of DC

f

minimum matching: \bullet : server of DC
 \circ : server of OPT
 connect pairs \bullet, \circ such that total length
 of connections is minimum

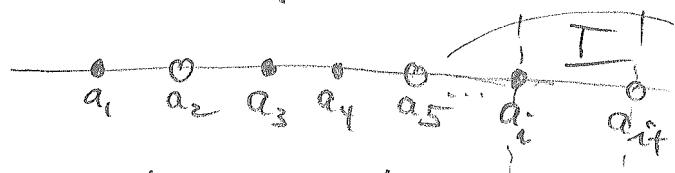
Examples



both
min
match

Let a_1, a_2, \dots, a_{2n} be the enumeration of all server positions of DC and OPT, in left-to-right order

for $1 \leq i \leq 2n$:



$$\delta_i := |\{\# \bullet - \# \circ \text{ with index } \leq i\}|$$

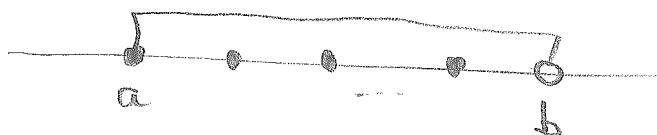
Lemma $M_{\min} = \text{cost of minimum matching}$

$$= \sum_{i=1}^{2n-1} \delta_i \cdot |a_{i+1} - a_i|$$

Proof: " \geq " at least δ_i edges must cross over interval I to partners of indices $\geq i+1$

" \leq " Construct minimum matching inductively, check that formula is preserved:

Pick leftmost position $a = a_i$, assume wlog $a = \bullet$
 let $b :=$ leftmost \circ position
 connect a, b , and delete both



[Lemma]

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Now we check if $\phi = k \cdot M_{\min} + \sum_{DC} \ell_i$ fulfills axioms (i), (ii), (iii) of potential functions. (12)

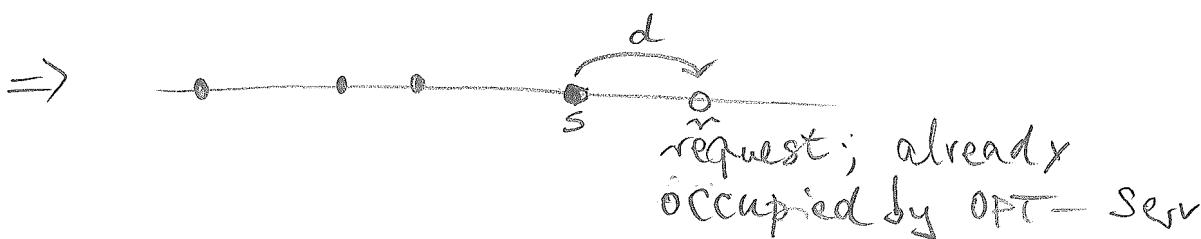
assume: first OPT moves then

(iii) $\phi \geq 0$ obvious

(ii) suppose OPT moves server by distance d in move e_i
 $\Rightarrow \sum_{DC} \ell_i$ does not change
 M_{\min} grows by $\leq d$

$$\Rightarrow \phi_i \leq \phi_{i-1} + kd = \phi_{i-1} + k \cdot \text{OPT}(e_i)$$

(i) suppose DC moves only one server by distance d in move e_i



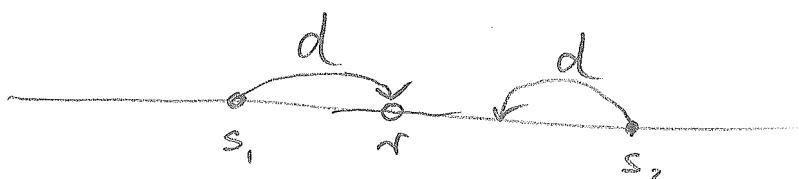
$$\Rightarrow \sum_{DC} \ell_i$$
 grows by $(k-1)d$

M_{\min} decreases by at least d , because in old minimum matching, s must have been matched to r (\rightarrow proof of previous lemma)

$$\Rightarrow \phi = k \cdot M_{\min} + \sum_{DC} \ell_i$$
 decreases by at least

$$\phi_i \leq \phi_{i-1} - d = \phi_{i-1} - DC(e_i)$$

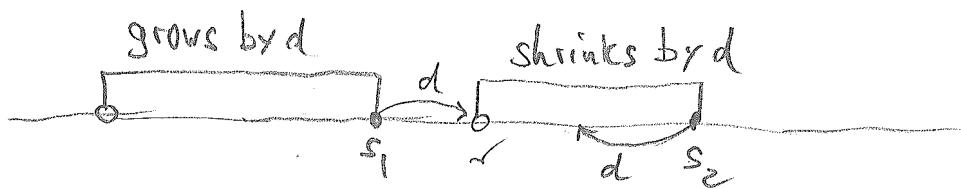
Suppose DC moves two servers by distance d in move e_i



h

in old minimum matching, one of s_1, s_2 must have been matched to r

otherwise



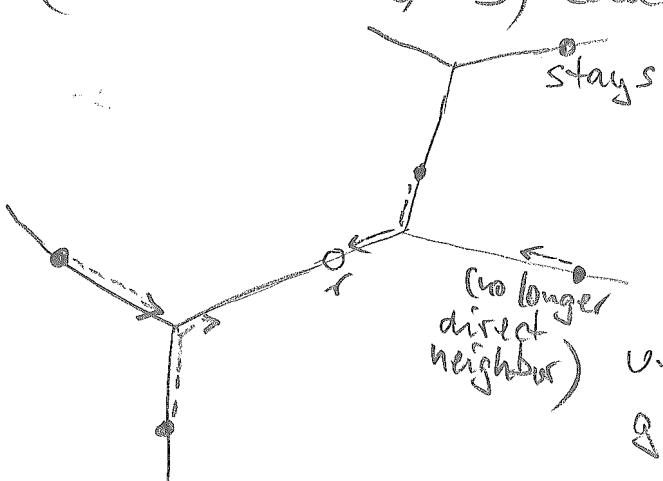
$\Rightarrow M_{\min}$ does not grow.

in \sum_{DC} : $|s_1 - s_2|$ shrinks by $2d$
all $|s_1 - s| + |s - s_2|$ remain unchanged

$\Rightarrow k \cdot M_{\min} + \sum_{DC}$ decreases by at least $2d$.

(Theorem)

Algorithm DC (and its analysis) can be generalized to trees:

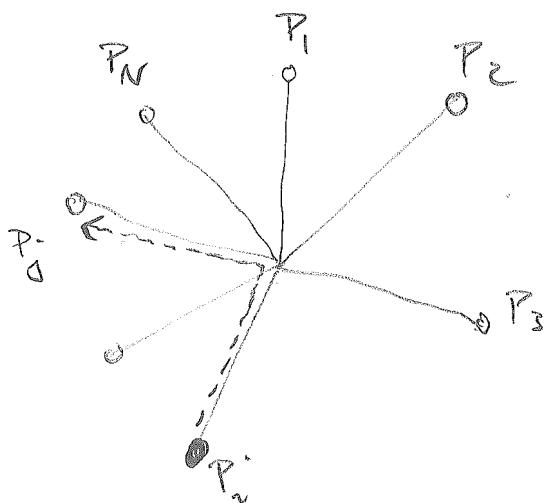


Only the direct neighbors of r move towards r until first server gets there

Theorem DC is k -competitive in trees.

Example: k servers on a star

(131)



interpretation

on request of P_j ,
server from P_i moves there

server locations

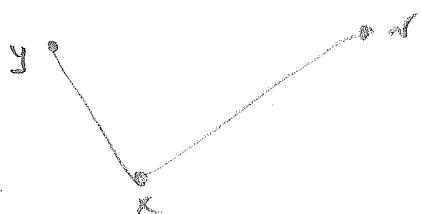
$\hat{=}$ memory pages stored
in cache of size k

on request for page j , page i gets evicted from
cache

algorithm DC \leftrightarrow "flush when full"
must be k -competitive!

Another interesting special case: 2 servers in \mathbb{R}^2

Definition



$$\text{slack}(x, y, r) := |xy| + |xr| - |yr|$$

≥ 0 by \triangle

Algorithm SC (= Slack coverage)

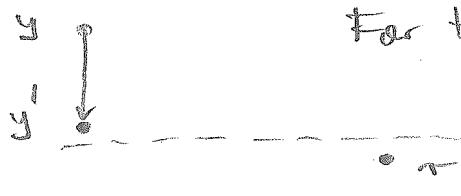
Suppose servers positioned at x and y ,
new request at r comes in, where $|xr| \leq |yr|$ \textcircled{O}

Then, move

server at y by $\frac{1}{2}\text{slack}(x, y, r)$ towards x

server at x to r

Lemma



For the new position, y'
of y -server:

$$|y'r| < |yr|$$

Proof: $\frac{1}{2}\text{slack}(x, y, r) = \frac{1}{2}(|xy| + |xr| - |yr|) \stackrel{(2)}{\leq} \frac{1}{2}|xy|$ Lemma

i what does SC do points on the line?

(13)

Case 1



$$\frac{1}{2} \text{slack}(x, y, r) = \frac{1}{2} (|xy| + |xr| - |yr|) \\ = |xr|$$

Case 2



$$\frac{1}{2} \text{slack}(x, y, r) = \frac{1}{2} (|xy| + |xr| - |yr|) \\ = 0$$

\Rightarrow SC = DC on the line!

Theorem For two servers in the plane, SC is 3-competitive

Proof Want to apply potential function approach with $\phi := 3M_{\min} + 2|xy| \geq 0$. (like before)

Need to prove 2 properties:

(i) When OPT moves distance D :

$$\Delta \phi = \phi_{\text{fin}} - \phi_i \leq 3D$$

After OPT
then SC

(ii) When SC moves distance D :

$$\Delta \phi \leq -D$$

Proof of (i) OPT moves server a distance D

$\Rightarrow |xy|$ does not change, M_{\min} grows by $\leq D$

proof of (ii)

assume $|x_r| \leq |y_r|$

(133)

and SC moves server from y by $\frac{1}{2} \text{slack}(x, y, r)$ to y'
server from x to r

$$\Rightarrow D = |x_r| + \frac{1}{2} \text{slack}(x, y, r) \quad \text{total distance moved by SC}$$

$$\text{Clear: } \Delta |xy| = |xy'| - |xy| \leq |ry| - |xy| \quad \text{Lemma}$$

to be determined: ΔM_{\min}

Let s_1, s_2 be the OPT-servers, $s_1 = r$ after serving request

Case 1 Before SC moves, $x \leftrightarrow s_1 = r$ in M_{\min}
 $y \leftrightarrow s_2$

$\Rightarrow M_{\min}$ decreases by at least $|x_r|$
increases by at most $\frac{1}{2} \text{slack}(x, y, r)$

as SC moves

$$\begin{aligned} \Rightarrow \Delta \phi &\leq 3 \left(\underbrace{\frac{1}{2} \text{slack}(x, y, r)}_{\frac{1}{2}(|xy| + |x_r| - |y_r|)} - |x_r| \right) + 2(|ry| - |xy|) \\ &= -|x_r| - \frac{1}{2}|xy| - \frac{1}{2}|x_r| + \frac{1}{2}|y_r| = -D \end{aligned}$$

Case 2 Before SC moves, $x \leftrightarrow s_2$ in M_{\min}
 $y \leftrightarrow s_1 = r$

\Rightarrow afterwards $x \leftrightarrow s_1 = r$ (identical)
 $y' \leftrightarrow s_2$

$$\Rightarrow \Delta M_{\min} \leq |ys_2| - |xs_2| - |y_r|$$

$$\triangleleft \quad |y'x| - |y_r| = |yx| - \frac{1}{\varepsilon} \text{slack}(x,y_r) - |y_r| \quad (134)$$

\triangleleft

$$\Rightarrow \Delta \phi \leq 3 \left(|yx| - \frac{1}{\varepsilon} |xy| - \frac{1}{\varepsilon} |xr| + \frac{1}{\varepsilon} |yr| - |y_r| \right) \\ + \underbrace{2|r_y| - 2|xy|}_{\leq \Delta |xy|} \\ = - |xr| - \frac{1}{\varepsilon} |xy| - \frac{1}{\varepsilon} |xr| + \frac{1}{\varepsilon} |yr| = - D.$$

Theorem

Best result known for general k , general metric spaces:

Theorem (Koutsopoulos, Papadimitriou '95)

There exists a $(2k-1)$ -competitive algorithm for the k -server problem in general metric spaces.

k -Server-Problem Is there a k -competitive algorithm?