

Online Motion Planning, SS 17
Exercise sheet 11
University of Bonn, Inst. for Computer Science, Dpt. I

- *You can hand in your written solutions until Wednesday, 12.07., 14:15, postbox in front of room E.01 LBH.*

Exercise 31: SearchRatio of a Grid (6 points)

We are searching for an unknown goal in one cell of a fixed 8×8 cell environment, starting at some fixed point s as given in Figure 1. The agent has no vision. We assume that moving from one cell to an adjacent cell always takes one step. We are looking for a search strategy that competes with the shortest path to an unknown goal in a cell.

Please turn the page!

a) $P_1 = (-1, 0)$, $P_2 = (-1, 2)$, $P_3 = (0, 2)$.

b) $P_1 = (-1, \frac{1}{2})$, $P_2 = (0, 1)$.

c) $P_1 = (-\frac{\sqrt{2}}{4}, \frac{2-\sqrt{2}}{4})$, $P_2 = (-\frac{1}{2}, \frac{1}{2})$, $P_3 = (-\frac{\sqrt{2}}{4}, \frac{2+\sqrt{2}}{4})$, $P_4 = (0, 1)$.

In part c), it suffices

- to provide a function that computes, for a given angle γ at the corner (see Figure 2), the distance the robot moves before it can look around the corner for the first time.
- to determine the distance moved by the optimal offline strategy, depending on γ .

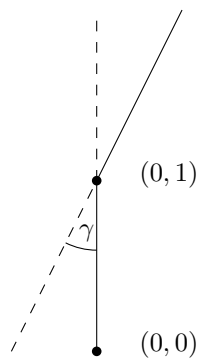


Figure 2: The angle γ .

Note that in this exercise we require that the additive constant, α , in the definition of the competitive factor is 0.