Online Motion Planning, SS 17 Exercise sheet 11

University of Bonn, Inst. for Computer Science, Dpt. I

• You can hand in your written solutions until Wednesday, 12.07., 14:15, postbox in front of room E.01 LBH.

Exercise 31: SearchRatio of a Grid (6 points)

We are searching for an unknown goal in one cell of a fixed 8×8 cell environment, starting at some fixed point s as given in Figure 1. The agent has no vision. We assume that moving from one cell to an adjacent cell always takes one step. We are looking for a search strategy that competes with the shortest path to an unknown goal in a cell.

Please turn the page!

Prove the following statements.

- 1. There is a search strategy that guarantees to find any goal with distance x from the start in $7 \cdot x$ steps.
- 2. There is no strategy that guarantees to find any goal at distance x with at most $5 \cdot x$ steps.
- 3. There is no strategy that guarantees to find any goal at distance x with at most $6 \cdot x$ steps.
- 4. Consider a 4×4 grid. Provide a strategy π and prove that the SearchRatio of the strategy π is minimal.

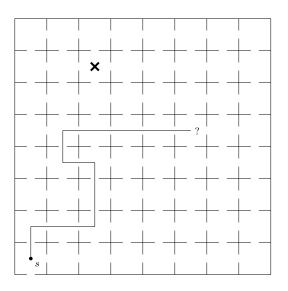


Figure 1: The $8 \times 8 = 64$ grid.

Exercise 32: Looking around a corner (6 points)

Compute the competitive factors of the following strategies for looking around a corner, given by the vertices of the exploration paths they specify. Here the starting point of our robot is the origin (0,0) of the coordinate system and the corner is at position (0,1).

- a) $P_1 = (-1, 0), P_2 = (-1, 2), P_3 = (0, 2).$
- b) $P_1 = (-1, \frac{1}{2}), P_2 = (0, 1).$
- c) $P_1 = \left(-\frac{\sqrt{2}}{4}, \frac{2-\sqrt{2}}{4}\right), P_2 = \left(-\frac{1}{2}, \frac{1}{2}\right), P_3 = \left(-\frac{\sqrt{2}}{4}, \frac{2+\sqrt{2}}{4}\right), P_4 = (0, 1).$

In part c), it suffices

- to provide a function that computes, for a given angle γ at the corner (see Figure 2), the distance the robot moves before it can look around the corner for the first time.
- to determine the distance moved by the optimal offline strategy, depending on γ .

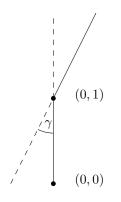


Figure 2: The angle γ .

Note that in this exercise we require that the additive constant, α , in the definition of the competitive factor is 0.